

Contractive Signatures with Recursive Types, Type Parameters, and Abstract Types^{*}

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Abstract. Although theories of equivalence or subtyping for recursive types have been extensively investigated, sophisticated interaction between recursive types and abstract types has gained little attention. The key idea behind type theories for recursive types is to use syntactic contractiveness, meaning every μ -bound variable occurs only under a type constructor such as \rightarrow or $*$. This syntactic contractiveness guarantees the existence of the unique solution of recursive equations and thus has been considered necessary for designing a sound theory for recursive types. However, in an advanced type system, such as OCaml, with recursive types, type parameters, and abstract types, we cannot easily define the syntactic contractiveness of types. In this paper, we investigate a sound type system for recursive types, type parameters, and abstract types. In particular, we develop a new semantic notion of contractiveness for types and signatures using mixed induction and coinduction, and show that our type system is sound with respect to the standard call-by-value operational semantics, which eliminates signature sealings. Moreover we show that while non-contractive types in signatures lead to unsoundness of the type system, they may be allowed in modules. We have also formalized the whole system and its type soundness proof in Coq.

1 Introduction

Recursive types are widely used features in most programming languages and the key constructs to exploit recursively defined data structures such as lists and trees. In type theory, there are two ways to exploit recursive types, namely by using the *iso-recursive* or *equi-recursive* formulation.

In the iso-recursive formulation, a recursive type $\mu X.\tau$ is considered isomorphic but not equal to its one-step unfolding $\{X \mapsto \mu X.\tau\}\tau$. Correspondingly the term language provides built-in coercion functions called *fold* and *unfold*, witnessing this isomorphism.

$$\begin{aligned} \text{fold} & : \{X \mapsto \mu X.\tau\}\tau \rightarrow \mu X.\tau \\ \text{unfold} & : \mu X.\tau \rightarrow \{X \mapsto \mu X.\tau\}\tau \end{aligned}$$

^{*} An expanded version of this paper, containing detailed proofs and omitted definitions, and the Coq development are available at <http://toccata.lri.fr/~im>.

Although in the iso-recursive formulation programs have to be annotated with `fold` and `unfold` coercion functions, this formulation usually simplifies typechecking in the presence of recursive types. For example, datatypes in SML [11] are a special form of iso-recursive types.

In contrast, the equi-recursive formulation defines a recursive type $\mu X.\tau$ to be equal to its one-step unfolding $\{X \mapsto \mu X.\tau\}\tau$ and does not require any coercion functions as in the iso-recursive formulation. For example, polymorphic variant and object types as implemented in OCaml [1] require structural recursive types and thus equi-recursive types. To use equi-recursive types, it suffices to add either of the two rules below into the type system:

$$\frac{\Gamma \vdash e : \tau \quad \tau \equiv \sigma}{\Gamma \vdash e : \sigma} \text{typ-eq} \qquad \frac{\Gamma \vdash e : \tau \quad \tau \leq \sigma}{\Gamma \vdash e : \sigma} \text{typ-sub}$$

Here the rule `typ-eq` exploits the equivalence relation \equiv between recursive types, and the rule `typ-sub` the subtyping relation \leq . The equi-recursive formulation makes it easier to write programs using recursive types, but it raises a tricky problem in typechecking: we need to decide when two recursive types are in the equivalence or subtyping relation. In response, several authors have investigated theories of equivalence or subtyping for equi-recursive types [2, 3, 6, 18].

The key idea behind type theories for equi-recursive types is to use syntactic contractiveness [9], meaning that given a recursive type $\mu X.\tau$, the use of the recursion variable X in τ must occur under a type constructor such as \rightarrow or $*$. In other words, non-contractive types such as $\mu X.X$ and `unit* $\mu X.X$` are rejected at the syntax level. For example, most previous work considers variants of the following type language:

$$\tau, \sigma ::= X \mid \tau \rightarrow \sigma \mid \mu X.(\tau \rightarrow \sigma)$$

The main reason for employing this syntactic contractiveness is to guarantee the existence of the unique solution of recursive equations introduced by equi-recursive types and obtain a sound type theory.

However, in an advanced type system, such as OCaml, with recursive types, type parameters, abstract types, and modules, we cannot easily define the syntactic contractiveness of types. To illustrate, consider the following code fragment which is allowed in OCaml using the “-rectypes” option. The “-rectypes” option allows arbitrary equi-recursive types.

```

module M : T = struct
  type 'a t = 'a
  type s = int and u = bool
  let f x = x
  let g x = x
end
let h x = M.g (M.f x)
let y = h 3

module type T = sig
  type 'a t
  type s = s t and u = u t
  val f : int -> s
  val g : u -> bool
end
(* run-time error *)

```

Under the usual interpretation of ML signature sealings, the module `M` correctly implements, or satisfies, the signature `T`. Moreover the types `s` and `u` in `T` are

considered contractive in OCaml since the type cycles are guarded by the parameterized abstract type \mathfrak{t} in T ; hence the signature T is well-formed. Furthermore the types \mathfrak{s} and \mathfrak{u} in T are structurally equivalent, and thus the values \mathfrak{h} and \mathfrak{y} are well-formed with types $\text{int} \rightarrow \text{bool}$ and bool , respectively. At run-time, however, the evaluation of \mathfrak{y} , *i.e.*, $\mathfrak{h} \ 3$, leads to an unknown constructor 3 of type bool , breaking type soundness.⁴

In this paper, we investigate a type system for equi-recursive types, type parameters, and abstract types. In our system, recursive types may be declared by using type definitions of the form $\text{type } \alpha \ t = \tau$ where both the type parameter α and the recursive type t may appear in the type τ .⁵ Abstract types may be declared by using the usual ML-style signature sealing operations (Section 2.1). For this system, we develop a new notion of semantic contractiveness for types and signatures using mixed induction and coinduction (Section 2.3). Our semantic contractiveness determines the types \mathfrak{s} and \mathfrak{u} in the signature T above to be non-contractive, and our type system rejects T . We then show that our type system with semantic contractiveness is sound with respect to the standard call-by-value operational semantics, which eliminates signature sealings (Section 2.4).

Another notable result is that even in the presence of non-contractive types in modules, we can develop a sound type system where well-typed programs cannot go wrong. This is particularly important since our type soundness result may give a strong hint about the soundness of OCaml, which allows us to define non-contractive types using recursive modules and signature sealings.

Our contributions are summarized as follows.

- To our knowledge, we are the first to consider a type system for equi-recursive types, type parameters, and abstract types, and define a type sound semantic notion of contractiveness.
- Since the OCaml type system allows both recursive types and abstract types, and non-contractive types in modules, our type soundness result gives a strong hint about how to establish the soundness of OCaml.
- We have formalized the whole system and its type soundness proof in Coq version 8.4. Our formalization extensively uses mixed induction and coinduction, so it may act as a good reference for using mixed induction and coinduction in Coq.

The remainder of the paper is organized as follows. Section 2 presents a type system for recursive types, type parameters, and abstract types. In particular, we consider a simple module system with a signature sealing operation and define a structural type equivalence and semantic contractiveness using mixed induction and coinduction. Section 3 discusses Coq mechanization and an algorithmic type equivalence and contractiveness. Section 4 discusses related work and Section 5 concludes.

⁴ We discovered the above bug together with Jacques Garrigue and it has been fixed in the development version of OCaml (available in the OCaml svn repository).

⁵ We do not use the usual μ -notation because encoding mutually recursive type definitions into μ -types requires type-level pairs and projection, complicating the theory. Moreover the use of type definitions better reflects the OCaml implementation.

Syntax

types	$\tau, \sigma ::= \text{unit} \mid \alpha \mid \tau \rightarrow \sigma \mid \tau_1 * \tau_2 \mid \tau t$
expressions	$e ::= () \mid x \mid \lambda x : \tau. e \mid e_1 e_2 \mid (e_1, e_2) \mid \pi_i(e) \mid \text{fix } x : \tau. e \mid l$
specifications	$D ::= \text{type } \alpha t \mid \text{type } \alpha t = \tau \mid \text{val } l : \tau$
definitions	$d_\tau ::= \text{type } \alpha t = \tau$ (type definitions) $d_e ::= \text{let } l = e$ (value definitions)
signatures	$S ::= \cdot \mid D, S$
modules	$M ::= (\overline{d_\tau}, \overline{d_e})$
programs	$P ::= (M, S, e) \mid (M, e)$

Well-formed types

$$\boxed{S; \Sigma \vdash \tau \text{ type}}$$

type variable sets $\Sigma ::= \cdot \mid \{\alpha\}$

Standard well-formedness rules for types are omitted.

$$\frac{S \ni \text{type } \alpha t \quad S; \Sigma \vdash \tau \text{ type}}{S; \Sigma \vdash \tau t \text{ type}} \text{ wft-abs} \quad \frac{S \ni \text{type } \alpha t = \sigma \quad S; \Sigma \vdash \tau \text{ type}}{S; \Sigma \vdash \tau t \text{ type}} \text{ wft-app}$$

Well-formed specifications and signatures

$$\boxed{S \vdash D \text{ ok}} \quad \boxed{S \text{ ok}}$$

$$\frac{}{S \vdash \text{type } \alpha t \text{ ok}} \text{ wfs-abs} \quad \frac{S; \{\alpha\} \vdash \tau \text{ type}}{S \vdash \text{type } \alpha t = \tau \text{ ok}} \text{ wfs-type} \quad \frac{S; \cdot \vdash \tau \text{ type}}{S \vdash \text{val } l : \tau \text{ ok}} \text{ wfs-val}$$

$$\frac{\text{BN}(S) \text{ distinct} \quad \forall D \in S, S \vdash D \text{ ok}}{S \text{ ok}} \text{ wf-sig}$$

Fig. 1. Syntax and well-formedness

2 A Type System $\lambda_{\text{abs}}^{\text{rec}}$

This section presents a type system $\lambda_{\text{abs}}^{\text{rec}}$ for recursive types, type parameters, and abstract types, permitting non-contractive types in modules. Section 2.1 presents the syntax and inference rules for well-formedness. Section 2.2 defines a structural type equivalence and Section 2.3 defines a semantic contractiveness using mixed induction and coinduction. Finally Section 2.4 presents a type soundness result with respect to the standard call-by-value operational semantics.

2.1 Syntax and Well-formedness

Figure 1 shows the syntax for $\lambda_{\text{abs}}^{\text{rec}}$ and inference rules for well-formedness. We use meta-variables α, β for type variables, s, t, u for type names, x, y, z for value variables, and l for value names. Both types and expressions are defined in the standard way as in the simply-typed λ -calculus except that they may refer to type definitions and value definitions in modules. For simplicity, we include simple signatures and modules only, which suffice to introduce abstract types, and exclude nested modules and functors. Abstract types are then introduced by a program of the form (M, S, e) , called a signature sealing, which hides the implementation details of the module M behind the signature S .

Recursive types are introduced by type definitions of the form $\text{type } \alpha t = \tau$ where τ may refer to the name t with no restriction. For example, we may define recursive types such as $\text{type } \alpha t = \alpha t \rightarrow \alpha t$ and $\text{type } \alpha t = \alpha t \rightarrow (\alpha * \alpha) t$. We also permit a non-contractive type definition such as $\text{type } \alpha t = \alpha t$ in a module but reject a non-contractive type specification in a signature, since the latter breaks type soundness. Any sequence \overline{d}_τ of type definitions (or type specifications) in modules (or signatures) may be mutually recursive, whereas no sequence \overline{d}_e of value definitions are mutually recursive. The main reason for this design choice is that our focus in this paper is to investigate the interaction between non-contractive recursive types and abstract types. Moreover, to simplify the discussion, we consider only those type constructors with a single parameter. We can easily add into the system nullary or multi-parameter type constructors.

As for well-formedness of types, we use a judgment $S; \Sigma \vdash \tau \text{ type}$ to mean that type τ is well-formed under context (S, Σ) . Here we use a type variable set Σ to denote either an empty set or a singleton set. We also use judgments $S \vdash D \text{ ok}$ and $S \text{ ok}$ to mean that specification D and signature S are well-formed, respectively. Most of the rules are standard, and we only remark that a signature S is well-formed only if all bound type names in S are distinct from each other and each type definition is well-formed under S (rule `wf-sig`). These well-formedness conditions for signatures allow us to define arbitrarily mutually recursive type definitions. In the remainder of the paper, we assume that every type and signature that we mention is well-formed, without explicitly saying so.

2.2 Type Equivalence

In this section, we define a type equivalence relation in terms of unfolding type definitions. The usual β -equivalence is then embedded into our type equivalence relation by means of unfolding. We use a judgment $S \vdash \tau \rightarrow \sigma$ to mean that type τ unfolds into σ by expanding a type name in τ into its definition under S . The rule `unfold` below, which is the only rule for unfolding type definitions, implements this idea and given a type application τt , it replaces type variable α with argument τ in definition σ of t .

$$\frac{S \ni \text{type } \alpha t = \sigma}{S \vdash \tau t \rightarrow \{\alpha \mapsto \tau\} \sigma} \text{ unfold}$$

We write $S \vdash \tau \rightarrow^* \sigma$ for the reflexive and transitive closure of unfolding. We say that a type τ is *vacuous* under signature S , if $\forall \tau', S \vdash \tau \rightarrow^* \tau'$ implies $\exists \tau'', S \vdash \tau' \rightarrow \tau''$. In other words, vacuous types are those types that allow us to unfold type definitions infinitely using the rule `unfold`.

The type equivalence relation is defined by nesting induction into coinduction. In order to structurally compare types for their equivalence, we should be able to check equivalence for vacuous types. While using induction to compare structures of types, we use coinduction to compare infinite unfoldings of types and thus to check equivalence for vacuous types. Figure 2 shows inference rules for type equivalence, defined using the rule `unfold`. We use a judgment

Coinductive type equivalence

$$\boxed{S; \Sigma \vdash \tau_1 \equiv \tau_2}$$

$$\frac{S; \Sigma \vdash \tau \equiv \sigma}{S; \Sigma \vdash \tau \equiv \sigma} \text{eq-ind} \quad \frac{S \vdash \tau \rightarrow \tau' \quad S \vdash \sigma \rightarrow \sigma' \quad S; \Sigma \vdash \tau' \equiv \sigma'}{S; \Sigma \vdash \tau \equiv \sigma} \text{eq-coind}$$

Inductive type equivalence

$$\boxed{S; \Sigma \vdash \tau_1 \stackrel{R}{\equiv} \tau_2}$$

$$\frac{}{S; \Sigma \vdash \text{unit} \stackrel{R}{\equiv} \text{unit}} \text{eq-unit} \quad \frac{}{S; \{\alpha\} \vdash \alpha \stackrel{R}{\equiv} \alpha} \text{eq-var} \quad \frac{S; \Sigma \vdash \tau_i R \sigma_i \quad (i = 1, 2)}{S; \Sigma \vdash \tau_1 \rightarrow \tau_2 \stackrel{R}{\equiv} \sigma_1 \rightarrow \sigma_2} \text{eq-fun}$$

$$\frac{S; \Sigma \vdash \tau_i R \sigma_i \quad (i = 1, 2)}{S; \Sigma \vdash \tau_1 * \tau_2 \stackrel{R}{\equiv} \sigma_1 * \sigma_2} \text{eq-prod} \quad \frac{S \ni \text{type } \alpha \ t \quad S; \Sigma \vdash \tau R \sigma}{S; \Sigma \vdash \tau \ t \stackrel{R}{\equiv} \sigma \ t} \text{eq-abs}$$

$$\frac{S \vdash \tau \rightarrow \tau' \quad S; \Sigma \vdash \tau' \stackrel{R}{\equiv} \sigma}{S; \Sigma \vdash \tau \stackrel{R}{\equiv} \sigma} \text{eq-lunfold} \quad \frac{S \vdash \sigma \rightarrow \sigma' \quad S; \Sigma \vdash \tau \stackrel{R}{\equiv} \sigma'}{S; \Sigma \vdash \tau \stackrel{R}{\equiv} \sigma} \text{eq-runfold}$$

Fig. 2. Type equivalence

$S; \Sigma \vdash \tau_1 \equiv \tau_2$ to mean that τ_1 and τ_2 are coinductively equivalent under context (S, Σ) and a judgment $S; \Sigma \vdash \tau_1 \stackrel{R}{\equiv} \tau_2$ to mean that τ_1 and τ_2 are inductively equivalent. Note that the inductive equivalence relation $\stackrel{R}{\equiv}$ is parameterized over a relation R , which is instantiated with the coinductive equivalence relation \equiv in the rule **eq-ind**. This way, we nest the inductive equivalence relation into the coinductive equivalence relation⁶. We use a double horizontal line for a coinductive rule and a single horizontal line for an inductive rule.

The rule **eq-coind** is a coinductive rule for checking equivalence between vacuous types. To show that two vacuous types τ and σ are equivalent, that is, $S; \Sigma \vdash \tau \equiv \sigma$, we repeatedly apply the rule **eq-coind**. When we get the very same proposition to be proved in the premise, the proof is completed by coinduction. Notably vacuous types are only equivalent to vacuous types. As for equivalence for types other than vacuous types, we use the rule **eq-ind**, which nests induction into coinduction, to compare their structures.

The inductive type equivalence compares structures of types. Given a pair of types, we apply the rule **eq-lunfold** or **eq-runfold** a finite number of times, unfolding type definitions, until we get a pair of the unit type, type variables, function types, or product types. Then we structurally compare them. Note that the rules **eq-lunfold** and **eq-runfold** are the only rules where induction plays a role. It is crucial that these rules are defined inductively; if we allow them to be used coinductively, a vacuous type becomes equivalent to any type. The rules **eq-unit** for the unit type and **eq-var** for type variables are standard. The rules **eq-fun** for function types, **eq-prod** for product types, and **eq-abs** for abstract types are where the inductive equivalence goes back to the coinductive equivalence.

⁶ A definition of the form $\nu X.F(X, \mu Y.G(X, Y))$.

Contractive types and signatures

$$\begin{array}{c}
\boxed{S \Downarrow \tau} \quad \boxed{S \Downarrow_C \tau} \quad \boxed{S \Downarrow} \\
\\
\frac{S \Downarrow \tau}{S \Downarrow \tau} \text{ c-coind} \quad \frac{}{S \Downarrow_C \text{ unit}} \text{ c-unit} \quad \frac{}{S \Downarrow_C \alpha} \text{ c-var} \quad \frac{(S, \tau_i) \in C \quad (i = 1, 2)}{S \Downarrow_C \tau_1 \rightarrow \tau_2} \text{ c-fun} \\
\\
\frac{(S, \tau_i) \in C \quad (i = 1, 2)}{S \Downarrow_C \tau_1 * \tau_2} \text{ c-prod} \quad \frac{S \ni \text{type } \alpha \ t \quad S \Downarrow_C \tau}{S \Downarrow_C \tau \ t} \text{ c-abs} \quad \frac{S \vdash \tau \rightarrow \sigma \quad S \Downarrow_C \sigma}{S \Downarrow_C \tau} \text{ c-type} \\
\\
\frac{\forall (\text{type } \alpha \ t = \tau) \in S, \ S \Downarrow \tau}{S \Downarrow} \text{ c-sig}
\end{array}$$

Fig. 3. Contractive types and signatures

With this definition of type equivalence, for example, now we prove that the types s and u in the signature T in the introduction are equivalent as follows:

$$\frac{T \ni \text{type } 'a \ t \quad \frac{}{T; \cdot \vdash s \equiv u} \text{ coinduction hypothesis}}{T; \cdot \vdash s \ t \equiv u \ t} \text{ eq-abs} \\
\frac{T; \cdot \vdash s \ t \equiv u \ t}{T; \cdot \vdash s \equiv u} \text{ eq-ind, eq-lunf, eq-runf}$$

Our type equivalence is indeed an equivalence relation, *i.e.*, reflexive, symmetric, and transitive (see the expanded version for the proof).

2.3 Contractive Types and Signatures

Given a program (M, S, e) , we restrict every type τ in a type specification $\text{type } \alpha \ t = \tau$ in S to be contractive to obtain type soundness as illustrated in the introduction. Intuitively a type is contractive if any sequence of its unfolding eventually produces a type constructor such as unit , α , \rightarrow , or $*$. A subtle case is a type application $\tau \ t$ where t is an abstract type: we require that τ be contractive. For instance, assuming t is an abstract type, $\text{type } \alpha \ s = (\alpha \ s * \alpha \ s) \ t$ and $\text{type } \alpha \ s = ((\alpha * \alpha) \ t) \ t$ are contractive, but $\text{type } \alpha \ s = (\alpha \ s) \ t$ is not. This way, we avoid the possibility of a type specification $\text{type } \alpha \ s = \tau$ in a signature to degenerate into $\text{type } \alpha \ s = \alpha \ s$ during subtyping.

Figure 3 shows inference rules for contractive types and signatures. We use two judgments $S \Downarrow \tau$ and $S \Downarrow_C \tau$ to define contractive types: the former to define coinductive contractiveness and the latter inductive contractiveness. The basic idea of using nested induction into coinduction is the same as for type equivalence. Note that the rule **c-coind** is the only coinductive rule for checking contractiveness of a type, which nests induction into coinduction.

The inductive contractiveness is defined using six rules: two axioms, two rules going back to the coinductive contractiveness, and two inductive rules for type applications. The unit type and type variables are by definition inductively contractive (rules **c-unit** and **c-var**). In the rules **c-fun** and **c-prod**, a function type $\tau_1 \rightarrow \tau_2$ and a product type $\tau_1 * \tau_2$ are inductively contractive under signature S if each component τ_i and S are related by C , which is instantiated with the

Well-typed definitions and modules

$$\boxed{S \vdash \bar{d}_e : S_e} \quad \boxed{\vdash M : S}$$

$$\frac{}{S \vdash \cdot : \cdot} \text{typ-emp} \quad \frac{S; \cdot \vdash e : \tau \quad S, \text{val } l : \tau \vdash \bar{d}_e : S_e}{S \vdash (\text{let } l = e, \bar{d}_e) : (\text{val } l : \tau, S_e)} \text{typ-val}$$

$$\frac{\bar{d}_\tau \text{ ok} \quad \bar{d}_\tau \vdash \bar{d}_e : S_e \quad \text{BN}(\bar{d}_e) \text{ distinct}}{\vdash (\bar{d}_\tau, \bar{d}_e) : (\bar{d}_\tau, S_e)} \text{typ-mod}$$

Well-typed programs

$$\boxed{\vdash P : (S, \tau)}$$

$$\frac{\vdash M : S' \quad S \Downarrow S' \leq S \quad S; \cdot \vdash e : \tau}{\vdash (M, S, e) : (S, \tau)} \text{typ-prog-seal} \quad \frac{\vdash M : S \quad S; \cdot \vdash e : \tau}{\vdash (M, e) : (S, \tau)} \text{typ-prog}$$

Reduction rules

$$\begin{array}{ll} \text{values} & v ::= () \mid \lambda x : \tau. e \mid (v_1, v_2) \\ \text{definition values} & d_v ::= \text{let } l = v \\ \text{module values} & V ::= (\bar{d}_\tau, \bar{d}_v) \\ \text{program values} & P_v ::= (V, v) \end{array}$$

$$\frac{}{(\overline{M, S, e}) \mapsto (\overline{M, e})} \text{red-p-seal}$$

$$\frac{M \mapsto M'}{(\overline{M, e}) \mapsto (\overline{M', e})} \text{red-p-mod} \quad \frac{\bar{d}_v \vdash e \mapsto e'}{(\overline{\bar{d}_\tau, \bar{d}_v, e}) \mapsto (\overline{\bar{d}_\tau, \bar{d}_v, e'})} \text{red-p-exp}$$

$$\frac{\bar{d}_v \vdash e \mapsto e'}{(\overline{\bar{d}_\tau, \bar{d}_v, \text{let } l = e, \bar{d}_e}) \mapsto (\overline{\bar{d}_\tau, \bar{d}_v, \text{let } l = e', \bar{d}_e})} \text{red-mod} \quad \frac{\bar{d}_v \ni \text{let } l = v}{\bar{d}_v \vdash l \mapsto v} \text{red-name}$$

Fig. 4. Typing rules and reduction rules

The key lemma for the preservation theorem is that type equivalence is preserved by subtyping. In the lemma below, the signature S_2 being contractive is crucial. For example, assuming \mathbf{S} is the inferred signature of the module \mathbf{M} in the introduction, although $\mathbf{S} \leq \mathbf{T}$ and $\mathbf{T}; \cdot \vdash \mathbf{s} \equiv \mathbf{t}$, we have $\mathbf{S}; \cdot \vdash \mathbf{s} \not\equiv \mathbf{t}$.

Lemma 2. *If $S_1 \leq S_2$, $S_2 \Downarrow$, and $S_2; \Sigma \vdash \tau \equiv \sigma$, then $S_1; \Sigma \vdash \tau \equiv \sigma$.*

Now using Lemma 2, we show that if a sealed program (M, S, e) is well-typed, the program (M, e) where the sealed signature S is eliminated is also well-typed (Lemma 3), which proves the most difficult case (4) of Theorem 4. We then prove other cases of Theorem 4 as usual using induction and case analysis.

Lemma 3 (Contractive signature elimination). *If $\vdash (M, S, e) : (S, \tau)$, then there exists S' such that $\vdash (M, e) : (S', \tau)$ and $S' \leq S$.*

Theorem 4 (Preservation).

- (1) *If $\vdash (\bar{d}_\tau, \bar{d}_v) : S$, $S; \cdot \vdash e : \tau$, and $\bar{d}_v \vdash e \mapsto e'$, then $S; \cdot \vdash e' : \tau$.*
- (2) *If $\vdash M : S$ and $M \mapsto M'$, then $\vdash M' : S$.*
- (3) *If $P = (M, e)$, $\vdash P : (S, \tau)$ and $P \mapsto P'$, then $\vdash P' : (S, \tau)$.*
- (4) *If $\vdash (M, S, e) : (S, \tau)$, then $\exists S'$ such that $\vdash M : S'$, $S' \leq S$, and $S'; \cdot \vdash e : \tau$.*

3 Discussion

3.1 Coq Mechanization

For the Coq mechanization, we use Mendler-style [10] coinductive rules for type equivalence and contractiveness in the style of Nakata and Uustalu [14], instead of the Park-style rules in Figures 2 and 3. The reason is that Coq’s syntactic guardedness condition for induction nested into coinduction is too weak to work with the Park-style rules. We cannot construct corecursive functions (coinductive proofs) that we need. For example, to enable Coq’s guarded corecursion, we use the following Mendler-style coinductive rule instead of the Park-style rule `eq-ind`:

$$\frac{R \subseteq \equiv \quad S; \Sigma \vdash \tau \stackrel{R}{\equiv} \sigma}{S; \Sigma \vdash \tau \equiv \sigma} \text{eq-ind}'$$

The main difference is that we use in the rule `eq-ind'` a relation R that is stronger than the coinductive equivalence relation \equiv . Hence, to build a coinductive proof, we need to find such a relation R , and in many cases we cannot just use \equiv for R . With this definition, the Park-style rules are derivable.

3.2 Algorithmic Type Equivalence and Contractiveness

Strictly speaking, equality of equi-recursive types with type parameters is decidable [4]. Solomon [17] has shown it to be equivalent to the equivalence problem for deterministic pushdown automata (DPDA), which has been shown decidable by Sénizergues [16]. There is, however, no known practical algorithm for DPDA-equivalence, and it is not known whether there exists any algorithm for unification either, which is required for type inference in the core language.

One possible approach to practical type equivalence would be to reject non-regular recursive types as in OCaml. We can then also algorithmically decide contractiveness of every type in a program by enumerating all the distinct type structures that can be obtained by unfolding each type used in the program and its subterms. Still we need a sound metatheory of non-regular recursive types to prove soundness of an OCaml-style recursive module system, because such types may be hidden behind signature sealings in the presence of recursive modules.

4 Related Work

The literature on subtyping for μ -types (hence without type definitions, type parameters, and abstract types) is abundant. In this setting, contractiveness can be checked syntactically: every μ -bound variable occurs under \rightarrow or $*$. We mention three landmark papers. Amadio and Cardelli [2] were the first to give a subtyping algorithm. They define subtyping in three ways, which are proved equivalent: an inclusion between unfoldings of μ -types into infinite trees, a subtyping algorithm, and an inductive axiomatization. Brandt and Henglein [3] give a new inductive axiomatization in which the underlying coinductive nature of

Amadio and Cardelli’s system is internalized by allowing, informally speaking, construction of circular proofs. Gapeyev *et al.* [6] is a good self-contained introduction to subtyping for recursive types, including historical notes on theories of recursive types. They define a subtyping relation on contractive μ -types as the greatest fixed point of a suitable generating function.

Danielsson and Altenkirch [5] present an axiomatization of subtyping for μ -types using induction nested into coinduction. They formalized the development in Agda, which supports induction nested into coinduction as a basic form. Komendantsky [8] conducted a similar project in Coq using the Mendler-style coinduction.

Recursive types are indispensable in theories of recursive modules since recursive modules allow us to indirectly introduce recursion in types that span across module boundaries. In this setting, one has to deal with a more expressive language for recursive types, which may include, for instance, higher-order type constructors, type definitions, and abstract types. Montagu and Rémy [12, 13] investigate existential types to model modular type abstraction in the context of a structural type system. They consider its extensions with recursion (*i.e.*, equi-recursive types without type parameters) and higher-order type constructors separately but do not investigate a combination of the two extensions. Crary *et al.* [4] first propose a type system for recursive modules using an inductive axiomatization of (coinductive) type equivalence for equi-recursive types with higher-order type constructors, type definitions, and abstract types. However, the metatheory of their axiomatization such as type soundness is not investigated. Rossberg and Dreyer [15] use equi-recursive types with inductive type equivalence (*i.e.*, they do not have a rule equivalent to *contract* in [2] to enable coinductive reasoning) to prove soundness of their mixin-style recursive module system. They do not intend to use equi-recursive types for the surface language. Our earlier work [7] on recursive modules considers equi-recursive types with type definitions and abstract types, but without type parameters. There we define a type equivalence relation using weak bisimilarity.

5 Conclusion and Future Work

This paper studies a type system for recursive types, type parameters, and abstract types. In particular, we investigate the interaction between non-contractive types and abstract types, and show that while non-contractive types in signatures lead to unsoundness of the type system, they may be allowed in modules. Our study is mainly motivated by OCaml, which allows us to define both abstract types and equi-recursive types with type parameters (with the “-rectypes” option). To obtain a sound type system, we develop a new notion of semantic contractiveness using mixed induction and coinduction and reject non-contractive types in signatures. We show that our type system is sound with respect to the standard call-by-value operational semantics, which eliminates signature sealings. We have also formalized the whole system and its soundness proof in Coq.

Future work includes extending our type system to the full-scale module system including recursive modules, nested modules, and higher-order functors.

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